

Julien Diperi, after obtaining his degrees in micromechanics in 2004 and working in various precision mechanics companies, joined the CNRS in 2010, becoming part of the Institute of Movement Sciences in Marseille. For 10 years, he focused his work on the integration of biomimetic sensors into flying and rolling robots, contributing to significant advances in the field of bio-inspired robotics. For the past three years, Julien Diperi has been a member of the Bio-Inspired Systems (SBI) team led by Professor Jean-Marc Linares, exploring topics such as the structure of bio-inspired parts modeled after long bones, mechanical joints derived from morphogenesis, and the development of bio-inspired actuators and dissipators.